Assignment: Scavenger Search

Description

This assignment is the next assignment in the Scavenger series. In the series, you will create an agent that can navigate from place to place in its world.

In this assignment, you will use the Problem, State, and Action classes with the tree search algorithm to find a safe path from your agent’s location to the goal location. You will not be required to move the agent to the goal, only find a path and display it to std::cout. You will repeat the search with breadth first and depth first frontiers.

Requirements

Do a Breadth First Tree Search

Modify your agent code to do a breadth first tree search from its current location to the goal location. If a path is found, display the action sequence required to reach the goal, and the charge your agent should have when it reaches the goal location. Also display the number of nodes generated, and maximum number of nodes stored.

Do a Depth First Tree Search

Modify your agent code to do a depth first tree search from its current location to the goal location. If a path is found, display the action sequence required to reach the goal, and the charge your agent should have when it reaches the goal location. Also display the number of nodes generated, and maximum number of nodes stored.

Notes

- Sample search code can be found in ai-agents/prog/Rectangle/RectDriver.cpp
- Use one of the search-small-world files for your runs.

Passoff

- Save the two sets of output to files. Submit the files to the CIT Submission System linked at the top of the page.